CONTENTS

1 Features 1
2 Contents 3
3 Indices and tables 39
Python Module Index 41
Index 43
CHAPTER
ONE

FEATURES

• Support focuses on Dask Arrays.
• Provides support for loading image files.
• Implements commonly used N-D filters.
• Includes a few N-D Fourier filters.
• Provides some functions for working with N-D label images.
• Supports a few N-D morphological operators.
2.1 Installation

2.1.1 Stable release

To install dask-image, run this command in your terminal:

```
$ conda install -c conda-forge dask-image
```

This is the preferred method to install dask-image, as it will always install the most recent stable release. If you don’t have conda installed, you can download and install it with the Anaconda distribution here. Alternatively, you can install dask-image with pip:

```
$ pip install dask-image
```

If you don’t have pip installed, this Python installation guide can guide you through the process. [Python installation guide](http://docs.python-guide.org/en/latest/starting/installation/)

2.1.2 From sources

The sources for dask-image can be downloaded from the Github repo.

You can either clone the public repository:

```
$ git clone git://github.com/dask/dask-image
```

Or download the tarball:

```
$ curl -OL https://github.com/dask/dask-image/tarball/master
```

Once you have a copy of the source, you can install it with:

```
$ python setup.py install
```
2.2 Quickstart

2.2.1 Importing dask-image

Import dask image is with an underscore, like this example:

```python
import dask_image.imread
import dask_image.ndfilters
```

2.2.2 Dask Examples

We highly recommend checking out the dask-image-quickstart.ipynb notebook (and any other dask-image example notebooks) at the dask-examples repository. You can find the dask-image quickstart notebook in the `applications` folder of this repository:

https://github.com/dask/dask-examples

The direct link to the notebook file is here:

https://github.com/dask/dask-examples/blob/master/applications/image-processing.ipynb

All the example notebooks are available to launch with mybinder and test out interactively.

2.2.3 An Even Quicker Start

You can read files stored on disk into a dask array by passing the filename, or regex matching multiple filenames into `imread()`.

```python
filename_pattern = 'path/to/image-*.png'
images = dask_image.imread.imread(filename_pattern)
```

If your images are parts of a much larger image, dask can stack, concatenate or block chunks together: http://docs.dask.org/en/latest/array-stack.html

Calling dask-image functions is also easy.

```python
import dask_image.ndfilters
blurred_image = dask_image.ndfilters.gaussian_filter(images, sigma=10)
```

Many other functions can be applied to dask arrays. See the dask_array_documentation for more detail on general array operations.

```python
result = function_name(images)
```

2.2.4 Further Reading

Good places to start include:

- The documentation on working with dask arrays: http://docs.dask.org/en/latest/array.html
## 2.3 Function Coverage

### 2.3.1 Coverage of dask-image vs scipy ndimage functions

This table shows which SciPy ndimage functions are supported by dask-image.

<table>
<thead>
<tr>
<th>Function name</th>
<th>SciPy ndimage</th>
<th>dask-image</th>
</tr>
</thead>
<tbody>
<tr>
<td>affine_transform</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>binary_closing</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>binary_dilation</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>binary_erosion</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>binary_fill_holes</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>binary_hit_or_miss</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>binary_opening</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>binary_propagation</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>black_tophat</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>center_of_mass</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>convolve</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>convolve1d</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>correlate</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>correlate1d</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>distance_transform_bf</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>distance_transform_cdt</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>distance_transform_edt</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>extrema</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>find_objects</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>fourier_ellipsoid</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>fourier_gaussian</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>fourier_shift</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>fourier_uniform</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>gaussian_filter</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>gaussian_filter1d</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>gaussian_gradient_magnitude</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>gaussian_laplace</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>generate_binary_structure</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>generic_filter</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>generic_filter1d</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>generic_gradient_magnitude</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>generic_laplace</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>geometric_transform</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>grey_closing</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>grey_dilation</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>grey_erosion</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>grey_opening</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>histogram</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>imread</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>iterate_structure</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>label</td>
<td>✓</td>
<td>✓</td>
</tr>
<tr>
<td>labeled_comprehensions</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>laplace</td>
<td>✓</td>
<td>✓</td>
</tr>
</tbody>
</table>

continues on next page
Table 1 – continued from previous page

<table>
<thead>
<tr>
<th>Function</th>
<th>Dask</th>
<th>NaN</th>
<th>Py</th>
<th>Cython</th>
</tr>
</thead>
<tbody>
<tr>
<td>map_coordinates</td>
<td>✓</td>
<td></td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>maximum</td>
<td>✓</td>
<td>✓</td>
<td></td>
<td></td>
</tr>
<tr>
<td>maximum_filter</td>
<td>✓</td>
<td></td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>maximum_filter1d</td>
<td>✓</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>maximum_position</td>
<td>✓</td>
<td></td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>mean</td>
<td>✓</td>
<td>✓</td>
<td></td>
<td></td>
</tr>
<tr>
<td>median</td>
<td>✓</td>
<td>✓</td>
<td></td>
<td></td>
</tr>
<tr>
<td>median_filter</td>
<td>✓</td>
<td></td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>minimum</td>
<td>✓</td>
<td>✓</td>
<td></td>
<td></td>
</tr>
<tr>
<td>minimum_filter</td>
<td>✓</td>
<td>✓</td>
<td></td>
<td></td>
</tr>
<tr>
<td>minimum_filter1d</td>
<td>✓</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>minimum_position</td>
<td>✓</td>
<td>✓</td>
<td></td>
<td></td>
</tr>
<tr>
<td>morphological_gradient</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>morphological_laplace</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>percentile_filter</td>
<td>✓</td>
<td>✓</td>
<td></td>
<td></td>
</tr>
<tr>
<td>prewitt</td>
<td>✓</td>
<td></td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>rank_filter</td>
<td>✓</td>
<td></td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>rotate</td>
<td>✓</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>shift</td>
<td>✓</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>sobel</td>
<td>✓</td>
<td>✓</td>
<td></td>
<td></td>
</tr>
<tr>
<td>spline_filter</td>
<td>✓</td>
<td></td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>spline_filter1d</td>
<td>✓</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>standard_deviation</td>
<td>✓</td>
<td>✓</td>
<td></td>
<td></td>
</tr>
<tr>
<td>sum</td>
<td>✓</td>
<td></td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>uniform_filter</td>
<td>✓</td>
<td>✓</td>
<td></td>
<td></td>
</tr>
<tr>
<td>uniform_filter1d</td>
<td>✓</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>variance</td>
<td>✓</td>
<td>✓</td>
<td></td>
<td></td>
</tr>
<tr>
<td>watershed_ift</td>
<td>✓</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>white_tophat</td>
<td>✓</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>zoom</td>
<td>✓</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

2.4 API

2.4.1 dask_image package

Subpackages

dask_image.dispatch package

dask_image.imread package

dask_image.imread.imread (fname, nframes=1, *, arraytype='numpy')

Read image data into a Dask Array.

Provides a simple, fast mechanism to ingest image data into a Dask Array.

Parameters

- **fname** (str) – A glob like string that may match one or multiple filenames.
• `nframes (int, optional)` – Number of the frames to include in each chunk (default: 1).
• `arraytype (str, optional)` – Array type for dask chunks. Available options: “numpy”, “cupy”.

Returns array – A Dask Array representing the contents of all image files.

Return type  dask.array.Array

dask_image.ndfilters package

dask_image.ndfilters.convolve (image, weights, mode='reflect', cval=0.0, origin=0)

Wrapped copy of “scipy.ndimage.filters.convolve”

Excludes the output parameter as it would not work with Dask arrays.

Original docstring:
Multidimensional convolution.
The array is convolved with the given kernel.

Parameters

• `image (array_like)` – The image array.
• `weights (array_like)` – Array of weights, same number of dimensions as image
• `mode (str or sequence, optional)` – The mode parameter determines how the image array is extended when the filter overlaps a border. By passing a sequence of modes with length equal to the number of dimensions of the image array, different modes can be specified along each axis. Default value is ‘reflect’. The valid values and their behavior is as follows:
  • ‘reflect’ (d c b a | a b c d | d c b a) The image is extended by reflecting about the edge of the last pixel.
  • ‘constant’ (k k k k | a b c d | k k k k) The image is extended by filling all values beyond the edge with the same constant value, defined by the `cval` parameter.
  • ‘nearest’ (a a a a | a b c d | d d d d) The image is extended by replicating the last pixel.
  • ‘mirror’ (d c b | a b c d | c b a) The image is extended by reflecting about the center of the last pixel.
  • ‘wrap’ (a b c d | a b c d | a b c d) The image is extended by wrapping around to the opposite edge.
• `cval (scalar, optional)` – Value to fill past edges of image if mode is ‘constant’. Default is 0.0
• `origin (int or sequence, optional)` – Controls the placement of the filter on the image array’s pixels. A value of 0 (the default) centers the filter over the pixel, with positive values shifting the filter to the left, and negative ones to the right. By passing a sequence of origins with length equal to the number of dimensions of the image array, different shifts can be specified along each axis.

Returns result – The result of convolution of image with weights.

Return type  ndarray

See also:
correlate()  Correlate an image with a kernel.

Notes

Each value in result is $C_i = \sum_j I_{i+k-j}W_j$, where $W$ is the weights kernel, $j$ is the n-D spatial index over $W$, $I$ is the image and $k$ is the coordinate of the center of $W$, specified by origin in the image parameters.

dask_image.ndfilters.correlate(image, weights, mode='reflect', cval=0.0, origin=0)

Wrapped copy of “scipy.ndimage.filters.correlate”

Excludes the output parameter as it would not work with Dask arrays.

Original docstring:
Multi-dimensional correlation.
The array is correlated with the given kernel.

Parameters

- **image** (*array_like*) – The image array.
- **weights** (*ndarray*) – array of weights, same number of dimensions as image
- **mode** (*str or sequence, optional*) – The mode parameter determines how the image array is extended when the filter overlaps a border. By passing a sequence of modes with length equal to the number of dimensions of the image array, different modes can be specified along each axis. Default value is ‘reflect’. The valid values and their behavior is as follows:
  - ’reflect’ (*d c b a | a b c d | d c b a*) The image is extended by reflecting about the edge of the last pixel.
  - ’constant’ (*k k k k | a b c d | k k k k*) The image is extended by filling all values beyond the edge with the same constant value, defined by the cval parameter.
  - ’nearest’ (*a a a a | a b c d | d d d d*) The image is extended by replicating the last pixel.
  - ’mirror’ (*d c b | a b c d | c b a*) The image is extended by reflecting about the center of the last pixel.
  - ’wrap’ (*a b c d | a b c d | a b c d*) The image is extended by wrapping around to the opposite edge.
- **cval** (*scalar, optional*) – Value to fill past edges of image if mode is ‘constant’. Default is 0.0.
- **origin** (*int or sequence, optional*) – Controls the placement of the filter on the image array’s pixels. A value of 0 (the default) centers the filter over the pixel, with positive values shifting the filter to the left, and negative ones to the right. By passing a sequence of origins with length equal to the number of dimensions of the image array, different shifts can be specified along each axis.

See also:

convolve()  Convolve an image with a kernel.

dask_image.ndfilters.gaussian_filter(image, sigma, order=0, mode='reflect', cval=0.0, truncate=4.0)

Wrapped copy of “scipy.ndimage.filters.gaussian_filter”

Excludes the output parameter as it would not work with Dask arrays.
Multidimensional Gaussian filter.

Parameters

- **image** (*array_like*) – The image array.
- **sigma** (*scalar or sequence of scalars*) – Standard deviation for Gaussian kernel. The standard deviations of the Gaussian filter are given for each axis as a sequence, or as a single number, in which case it is equal for all axes.
- **order** (*int or sequence of ints, optional*) – The order of the filter along each axis is given as a sequence of integers, or as a single number. An order of 0 corresponds to convolution with a Gaussian kernel. A positive order corresponds to convolution with that derivative of a Gaussian.
- **mode** (*str or sequence, optional*) – The mode parameter determines how the image array is extended when the filter overlaps a border. By passing a sequence of modes with length equal to the number of dimensions of the image array, different modes can be specified along each axis. Default value is ‘reflect’. The valid values and their behavior is as follows:
  - 'reflect' (*d c b a | a b c d | d c b a*) The image is extended by reflecting about the edge of the last pixel.
  - 'constant' (*k k k k | a b c d | k k k k*) The image is extended by filling all values beyond the edge with the same constant value, defined by the *cval* parameter.
  - 'nearest' (*a a a a | a b c d | d d d d*) The image is extended by replicating the last pixel.
  - 'mirror' (*d c b a | a b c d | c b a*) The image is extended by reflecting about the center of the last pixel.
  - 'wrap' (*a b c d | a b c d | a b c d*) The image is extended by wrapping around to the opposite edge.
- **cval** (*scalar, optional*) – Value to fill edges of image if mode is ‘constant’. Default is 0.0.
- **truncate** (*float*) – Truncate the filter at this many standard deviations. Default is 4.0.

Returns **gaussian_filter** – Returned array of same shape as image.

Return type : *ndarray*

Notes

The multidimensional filter is implemented as a sequence of one-dimensional convolution filters. The intermediate arrays are stored in the same data type as the output. Therefore, for output types with a limited precision, the results may be imprecise because intermediate results may be stored with insufficient precision.
• **image** *(array_like)* – The image array.

• **sigma** *(scalar or sequence of scalars)* – The standard deviations of the Gaussian filter are given for each axis as a sequence, or as a single number, in which case it is equal for all axes.

• **mode** *(str or sequence, optional)* – The mode parameter determines how the image array is extended when the filter overlaps a border. By passing a sequence of modes with length equal to the number of dimensions of the image array, different modes can be specified along each axis. Default value is ‘reflect’. The valid values and their behavior is as follows:

  * **reflect** *(d c b a | a b c d | d c b a)* The image is extended by reflecting about the edge of the last pixel.

  * **constant** *(k k k k | a b c d | k k k k)* The image is extended by filling all values beyond the edge with the same constant value, defined by the cval parameter.

  * **nearest** *(a a a a | a b c d | d d d d)* The image is extended by replicating the last pixel.

  * **mirror** *(d c b | a b c d | c b a)* The image is extended by reflecting about the center of the last pixel.

  * **wrap** *(a b c d | a b c d | a b c d)* The image is extended by wrapping around to the opposite edge.

  • **cval** *(scalar, optional)* – Value to fill past edges of image if mode is ‘constant’. Default is 0.0.

• **keyword arguments will be passed to gaussian_filter()** *(Extra)* –

**Returns** **gaussian_gradient_magnitude** – Filtered array. Has the same shape as image.

**Return type** *ndarray*

```python
dask_image.ndfilters.gaussian_laplace(image, sigma, mode='reflect', cval=0.0, truncate=4.0, **kwargs)
```

Wrapped copy of “scipy.ndimage.filters.gaussian_laplace”

Excludes the output parameter as it would not work with Dask arrays.

Original docstring:

Multidimensional Laplace filter using gaussian second derivatives.

**Parameters**

• **image** *(array_like)* – The image array.

• **sigma** *(scalar or sequence of scalars)* – The standard deviations of the Gaussian filter are given for each axis as a sequence, or as a single number, in which case it is equal for all axes.

• **mode** *(str or sequence, optional)* – The mode parameter determines how the image array is extended when the filter overlaps a border. By passing a sequence of modes with length equal to the number of dimensions of the image array, different modes can be specified along each axis. Default value is ‘reflect’. The valid values and their behavior is as follows:

  * **reflect** *(d c b a | a b c d | d c b a)* The image is extended by reflecting about the edge of the last pixel.

  * **constant** *(k k k k | a b c d | k k k k)* The image is extended by filling all values beyond the edge with the same constant value, defined by the cval parameter.
'nearest' (a a a a | a b c d | d d d d) The image is extended by replicating the last pixel.

'mirror' (d c b | a b c d | c b a) The image is extended by reflecting about the center of the last pixel.

'wrap' (a b c d | a b c d | a b c d) The image is extended by wrapping around to the opposite edge.

- **cval** (scalar, optional) – Value to fill past edges of image if mode is ‘constant’. Default is 0.0.

**keyword arguments will be passed to gaussian_filter()** (Extra)

```
dask_image.ndfilters.generic_filter(image, function, size=None, footprint=None, mode='reflect', cval=0.0, origin=0, extra_arguments=(), extra_keywords={})
```

Wrapped copy of “scipy.ndimage.filters.generic_filter”

Excludes the output parameter as it would not work with Dask arrays.

Original docstring:

Calculate a multi-dimensional filter using the given function.

At each element the provided function is called. The image values within the filter footprint at that element are passed to the function as a 1D array of double values.

**Parameters**

- **image** (array_like) – The image array.
- **function** (callable, scipy.LowLevelCallable) – Function to apply at each element.
- **size** (scalar or tuple, optional) – See footprint, below. Ignored if footprint is given.
- **footprint** (array, optional) – Either size or footprint must be defined. size gives the shape that is taken from the image array, at every element position, to define the image to the filter function. footprint is a boolean array that specifies (implicitly) a shape, but also which of the elements within this shape will get passed to the filter function. Thus size=(n,m) is equivalent to footprint=np.ones((n,m)). We adjust size to the number of dimensions of the image array, so that, if the image array is shape (10,10,10), and size is 2, then the actual size used is (2,2,2). When footprint is given, size is ignored.
- **mode** (str or sequence, optional) – The mode parameter determines how the image array is extended when the filter overlaps a border. By passing a sequence of modes with length equal to the number of dimensions of the image array, different modes can be specified along each axis. Default value is ‘reflect’. The valid values and their behavior is as follows:
  - 'reflect' (d c b a | a b c d | d c b a) The image is extended by reflecting about the edge of the last pixel.
  - 'constant' (k k k k | a b c d | k k k k) The image is extended by filling all values beyond the edge with the same constant value, defined by the cval parameter.
  - 'nearest' (a a a a | a b c d | d d d d) The image is extended by replicating the last pixel.
  - 'mirror' (d c b | a b c d | c b a) The image is extended by reflecting about the center of the last pixel.
  - 'wrap' (a b c d | a b c d | a b c d) The image is extended by wrapping around to the opposite edge.
• **cval** (*scalar, optional*) – Value to fill past edges of image if `mode` is ‘constant’. Default is 0.0.

• **origin** (*int or sequence, optional*) – Controls the placement of the filter on the image array’s pixels. A value of 0 (the default) centers the filter over the pixel, with positive values shifting the filter to the left, and negative ones to the right. By passing a sequence of origins with length equal to the number of dimensions of the image array, different shifts can be specified along each axis.

• **extra_arguments** (*sequence, optional*) – Sequence of extra positional arguments to pass to passed function.

• **extra_keywords** (*dict, optional*) – dict of extra keyword arguments to pass to passed function.

**Notes**

This function also accepts low-level callback functions with one of the following signatures and wrapped in `scipy.LowLevelCallable`:

```python
int callback(double *buffer, npy_intp filter_size,
              double *return_value, void *user_data)
int callback(double *buffer, intptr_t filter_size,
              double *return_value, void *user_data)
```

The calling function iterates over the elements of the image and output arrays, calling the callback function at each element. The elements within the footprint of the filter at the current element are passed through the `buffer` parameter, and the number of elements within the footprint through `filter_size`. The calculated value is returned in `return_value`. `user_data` is the data pointer provided to `scipy.LowLevelCallable` as-is.

The callback function must return an integer error status that is zero if something went wrong and one otherwise. If an error occurs, you should normally set the python error status with an informative message before returning, otherwise a default error message is set by the calling function.

In addition, some other low-level function pointer specifications are accepted, but these are for backward compatibility only and should not be used in new code.

dask_image.ndfilters.laplace (*image, mode=’reflect’, cval=0.0*)

Wrapped copy of “scipy.ndimage.filters.laplace”

Excludes the output parameter as it would not work with Dask arrays.

Original docstring:

N-dimensional Laplace filter based on approximate second derivatives.

**Parameters**

• **image** (*array_like*) – The image array.

• **mode** (*str or sequence, optional*) – The mode parameter determines how the image array is extended when the filter overlaps a border. By passing a sequence of modes with length equal to the number of dimensions of the image array, different modes can be specified along each axis. Default value is ‘reflect’. The valid values and their behavior is as follows:

  • **’reflect’** (*d c b a | a b c d | d c b a*) The image is extended by reflecting about the edge of the last pixel.
dask-image Documentation, Release 0.4.0+0.g1322e24.dirty

'constant' (k k k k \(\text{a b c d} | k k k k\)) The image is extended by filling all values beyond the edge with the same constant value, defined by the \textit{cval} parameter.

'nearest' (a a a a \(\text{a b c d} | d d d d\)) The image is extended by replicating the last pixel.

'mirror' (d c b \(| a b c d | c b a\)) The image is extended by reflecting about the center of the last pixel.

'wrap' (a b c d \(| a b c d | a b c d\)) The image is extended by wrapping around to the opposite edge.

• \textit{cval} (scalar, optional) – Value to fill past edges of image if \textit{mode} is ‘constant’. Default is 0.0.

\texttt{dask_image.ndfilters.maximum\_filter(image, size=None, footprint=None, mode='reflect', cval=0.0, origin=0)}

Wrapped copy of “scipy.ndimage.filters.maximum\_filter” Excludes the output parameter as it would not work with Dask arrays.

Original docstring:

Calculate a multi-dimensional maximum filter.

\textbf{Parameters}

• \textit{image} (array\_like) – The image array.

• \textit{size} (scalar or tuple, optional) – See footprint, below. Ignored if footprint is given.

• \textit{footprint} (array, optional) – Either \textit{size} or \textit{footprint} must be defined. \textit{size} gives the shape that is taken from the image array, at every element position, to define the image to the filter function. \textit{footprint} is a boolean array that specifies (implicitly) a shape, but also which of the elements within this shape will get passed to the filter function. Thus \texttt{size=(n,m)} is equivalent to \texttt{footprint=np.ones((n,m))}. We adjust \textit{size} to the number of dimensions of the image array, so that, if the image array is shape (10,10,10), and \textit{size} is 2, then the actual size used is (2,2,2). When \textit{footprint} is given, \textit{size} is ignored.

• \textit{mode} (str or sequence, optional) – The \textit{mode} parameter determines how the image array is extended when the filter overlaps a border. By passing a sequence of modes with length equal to the number of dimensions of the image array, different modes can be specified along each axis. Default value is ‘reflect’. The valid values and their behavior is as follows:

  'reflect' (d c b a \(| a b c d | d c b a\)) The image is extended by reflecting about the edge of the last pixel.

  'constant' (k k k k \(| a b c d | k k k k\)) The image is extended by filling all values beyond the edge with the same constant value, defined by the \textit{cval} parameter.

  'nearest' (a a a a \(| a b c d | d d d d\)) The image is extended by replicating the last pixel.

  'mirror' (d c b \(| a b c d | c b a\)) The image is extended by reflecting about the center of the last pixel.

  'wrap' (a b c d \(| a b c d | a b c d\)) The image is extended by wrapping around to the opposite edge.

• \textit{cval} (scalar, optional) – Value to fill past edges of image if \textit{mode} is ‘constant’. Default is 0.0.

• \textit{origin} (int or sequence, optional) – Controls the placement of the filter on the image array’s pixels. A value of 0 (the default) centers the filter over the pixel, with
positive values shifting the filter to the left, and negative ones to the right. By passing
a sequence of origins with length equal to the number of dimensions of the image array,
different shifts can be specified along each axis.

**Returns** maximum_filter – Filtered array. Has the same shape as `image`.

**Return type** ndarray

dask_image.ndfilters.median_filter(image, size=None, footprint=None, mode='reflect',
cval=0.0, origin=0)

Wrapped copy of “scipy.ndimage.filters.median_filter”

Excludes the output parameter as it would not work with Dask arrays.

Original docstring:

Calculate a multidimensional median filter.

**Parameters**

- **image** ([array_like]) – The image array.
- **size** ([scalar or tuple, optional]) – See footprint, below. Ignored if footprint is
given.
- **footprint** ([array, optional]) – Either `size` or `footprint` must be defined. `size` gives
the shape that is taken from the image array, at every element position, to define the image
to the filter function. `footprint` is a boolean array that specifies (implicitly) a shape, but
also which of the elements within this shape will get passed to the filter function. Thus
`size=(n,m)` is equivalent to `footprint=np.ones((n,m))`. We adjust `size` to the
number of dimensions of the image array, so that, if the image array is shape (10,10,10), and
`size` is 2, then the actual size used is (2,2,2). When `footprint` is given, `size` is ignored.
- **mode** ([str or sequence, optional]) – The `mode` parameter determines how the
image array is extended when the filter overlaps a border. By passing a sequence of modes
with length equal to the number of dimensions of the image array, different modes can be
specified along each axis. Default value is ‘reflect’. The valid values and their behavior is
as follows:
  - **reflect** *(d c b a | a b c d | d c b a)* The image is extended by reflecting about the edge of
the last pixel.
  - **constant** *(k k k k | a b c d | k k k k)* The image is extended by filling all values beyond the
edge with the same constant value, defined by the `cval` parameter.
  - **nearest** *(a a a a | a b c d | d d d d)* The image is extended by replicating the last pixel.
  - **mirror** *(d c b | a b c d | c b a)* The image is extended by reflecting about the center of
the last pixel.
  - **wrap** *(a b c d | a b c d | a b c d)* The image is extended by wrapping around to the oppo-
site edge.
- **cval** ([scalar, optional]) – Value to fill past edges of image if `mode` is ‘constant’.Default is 0.0.
- **origin** ([int or sequence, optional]) – Controls the placement of the filter on
the image array’s pixels. A value of 0 (the default) centers the filter over the pixel, with
positive values shifting the filter to the left, and negative ones to the right. By passing
a sequence of origins with length equal to the number of dimensions of the image array,
different shifts can be specified along each axis.

**Returns** median_filter – Filtered array. Has the same shape as `image`. 
Return type  ndarray
dask_image.ndfilters.minimum_filter(image, size=None, footprint=None, mode='reflect', cval=0.0, origin=0)
Wrapped copy of “scipy.ndimage.filters.minimum_filter”
Excludes the output parameter as it would not work with Dask arrays.
Original docstring:
Calculate a multi-dimensional minimum filter.

Parameters

- **image (array_like)** – The image array.
- **size (scalar or tuple, optional)** – See footprint, below. Ignored if footprint is given.
- **footprint (array, optional)** – Either size or footprint must be defined. size gives the shape that is taken from the image array, at every element position, to define the image to the filter function. footprint is a boolean array that specifies (implicitly) a shape, but also which of the elements within this shape will get passed to the filter function. Thus size=(n,m) is equivalent to footprint=np.ones((n,m)). We adjust size to the number of dimensions of the image array, so that, if the image array is shape (10,10,10), and size is 2, then the actual size used is (2,2,2). When footprint is given, size is ignored.
- **mode (str or sequence, optional)** – The mode parameter determines how the image array is extended when the filter overlaps a border. By passing a sequence of modes with length equal to the number of dimensions of the image array, different modes can be specified along each axis. Default value is ‘reflect’. The valid values and their behavior is as follows:
  - 'reflect' (d c b a \| a b c d \| d c b a) The image is extended by reflecting about the edge of the last pixel.
  - 'constant' (k k k k \| a b c d \| k k k k) The image is extended by filling all values beyond the edge with the same constant value, defined by the cval parameter.
  - 'nearest' (a a a a \| a b c d \| d d d d) The image is extended by replicating the last pixel.
  - 'mirror' (d c b \| a b c d \| c b a) The image is extended by reflecting about the center of the last pixel.
  - 'wrap' (a b c d \| a b c d \| a b c d) The image is extended by wrapping around to the opposite edge.
- **cval (scalar, optional)** – Value to fill past edges of image if mode is ‘constant’. Default is 0.0.
- **origin (int or sequence, optional)** – Controls the placement of the filter on the image array’s pixels. A value of 0 (the default) centers the filter over the pixel, with positive values shifting the filter to the left, and negative ones to the right. By passing a sequence of origins with length equal to the number of dimensions of the image array, different shifts can be specified along each axis.

Returns  minimum_filter – Filtered array. Has the same shape as image.

Return type  ndarray
dask_image.ndfilters.percentile_filter(image, percentile, size=None, footprint=None, mode='reflect', cval=0.0, origin=0)
Wrapped copy of “scipy.ndimage.filters.percentile_filter”
Excludes the output parameter as it would not work with Dask arrays.

Original docstring:

Calculate a multi-dimensional percentile filter.

Parameters

- **image** *(array_like)* – The image array.
- **percentile** *(scalar)* – The percentile parameter may be less than zero, i.e., percentile = -20 equals percentile = 80
- **size** *(scalar or tuple, optional)* – See footprint, below. Ignored if footprint is given.
- **footprint** *(array, optional)* – Either size or footprint must be defined. size gives the shape that is taken from the image array, at every element position, to define the image to the filter function. footprint is a boolean array that specifies (implicitly) a shape, but also which of the elements within this shape will get passed to the filter function. Thus size=(n,m) is equivalent to footprint=np.ones((n,m)). We adjust size to the number of dimensions of the image array, so that, if the image array is shape (10,10,10), and size is 2, then the actual size used is (2,2,2). When footprint is given, size is ignored.
- **mode** *(str or sequence, optional)* – The mode parameter determines how the image array is extended when the filter overlaps a border. By passing a sequence of modes with length equal to the number of dimensions of the image array, different modes can be specified along each axis. Default value is ‘reflect’. The valid values and their behavior is as follows:
  - ‘reflect’ *(d c b a | a b c d | d c b a)* The image is extended by reflecting about the edge of the last pixel.
  - ‘constant’ *(k k k k | a b c d | k k k k)* The image is extended by filling all values beyond the edge with the same constant value, defined by the cval parameter.
  - ‘nearest’ *(a a a a | a b c d | d d d d)* The image is extended by replicating the last pixel.
  - ‘mirror’ *(d c b | a b c d | c b a)* The image is extended by reflecting about the center of the last pixel.
  - ‘wrap’ *(a b c d | a b c d | a b c d)* The image is extended by wrapping around to the opposite edge.
- **cval** *(scalar, optional)* – Value to fill past edges of image if mode is ‘constant’. Default is 0.0.
- **origin** *(int or sequence, optional)* – Controls the placement of the filter on the image array’s pixels. A value of 0 (the default) centers the filter over the pixel, with positive values shifting the filter to the left, and negative ones to the right. By passing a sequence of origins with length equal to the number of dimensions of the image array, different shifts can be specified along each axis.

Returns **percentile_filter** – Filtered array. Has the same shape as image.

Return type  ndarray

dask_image.ndfilters.prewitt(image, axis=-1, mode='reflect', cval=0.0)

Wrapped copy of “scipy.ndimage.filters.prewitt”

Excludes the output parameter as it would not work with Dask arrays.

Original docstring:
Calculate a Prewitt filter.

Parameters

- **image (array_like)** – The image array.
- **axis (int, optional)** – The axis of `image` along which to calculate. Default is -1.
- **mode (str or sequence, optional)** – The mode parameter determines how the image array is extended when the filter overlaps a border. By passing a sequence of modes with length equal to the number of dimensions of the image array, different modes can be specified along each axis. Default value is 'reflect'. The valid values and their behavior is as follows:
  - 'reflect' (d c b a | a b c d | d c b a) The image is extended by reflecting about the edge of the last pixel.
  - 'constant' (k k k k | a b c d | k k k k) The image is extended by filling all values beyond the edge with the same constant value, defined by the cval parameter.
  - 'nearest' (a a a a | a b c d | d d d d) The image is extended by replicating the last pixel.
  - 'mirror' (d c b | a b c d | c b a) The image is extended by reflecting about the center of the last pixel.
  - 'wrap' (a b c d | a b c d | a b c d) The image is extended by wrapping around to the opposite edge.
- **cval (scalar, optional)** – Value to fill past edges of image if mode is 'constant'. Default is 0.0.

```python
import dask_image

dask_image.ndfilters.rank_filter(image, rank, size=None, footprint=None, mode='reflect', cval=0.0, origin=0)
```

Wrapped copy of “scipy.ndimage.filters.rank_filter”

Excludes the output parameter as it would not work with Dask arrays.

Original docstring:

Calculate a multi-dimensional rank filter.

Parameters

- **image (array_like)** – The image array.
- **rank (int)** – The rank parameter may be less then zero, i.e., rank = -1 indicates the largest element.
- **size (scalar or tuple, optional)** – See footprint, below. Ignored if footprint is given.
- **footprint (array, optional)** – Either size or footprint must be defined. size gives the shape that is taken from the image array, at every element position, to define the image to the filter function. footprint is a boolean array that specifies (implicitly) a shape, but also which of the elements within this shape will get passed to the filter function. Thus size=(n,m) is equivalent to footprint=np.ones((n,m)). We adjust size to the number of dimensions of the image array, so that, if the image array is shape (10,10,10), and size is 2, then the actual size used is (2,2,2). When footprint is given, size is ignored.
- **mode (str or sequence, optional)** – The mode parameter determines how the image array is extended when the filter overlaps a border. By passing a sequence of modes with length equal to the number of dimensions of the image array, different modes can be specified along each axis. Default value is 'reflect'. The valid values and their behavior is as follows:
'reflect' (d c b a | a b c d | d c b a) The image is extended by reflecting about the edge of the last pixel.

'constant' (k k k k | a b c d | k k k k) The image is extended by filling all values beyond the edge with the same constant value, defined by the cval parameter.

'nearest' (a a a a | a b c d | d d d d) The image is extended by replicating the last pixel.

'mirror' (d c b | a b c d | c b a) The image is extended by reflecting about the center of the last pixel.

'wrap' (a b c d | a b c d | a b c d) The image is extended by wrapping around to the opposite edge.

- cval (scalar, optional) – Value to fill past edges of image if mode is ‘constant’. Default is 0.0.
- origin (int or sequence, optional) – Controls the placement of the filter on the image array’s pixels. A value of 0 (the default) centers the filter over the pixel, with positive values shifting the filter to the left, and negative ones to the right. By passing a sequence of origins with length equal to the number of dimensions of the image array, different shifts can be specified along each axis.

Returns rank_filter – Filtered array. Has the same shape as image.

Return type ndarray

dask_image.ndfilters.sobel (image, axis=-1, mode='reflect', cval=0.0)

Wrapped copy of “scipy.ndimage.filters.sobel”

Excludes the output parameter as it would not work with Dask arrays.

Original docstring:

Calculate a Sobel filter.

Parameters

- image (array_like) – The image array.
- axis (int, optional) – The axis of image along which to calculate. Default is -1.
- mode (str or sequence, optional) – The mode parameter determines how the image array is extended when the filter overlaps a border. By passing a sequence of modes with length equal to the number of dimensions of the image array, different modes can be specified along each axis. Default value is ‘reflect’. The valid values and their behavior is as follows:
  - 'reflect' (d c b a | a b c d | d c b a) The image is extended by reflecting about the edge of the last pixel.
  - 'constant' (k k k k | a b c d | k k k k) The image is extended by filling all values beyond the edge with the same constant value, defined by the cval parameter.
  - 'nearest' (a a a a | a b c d | d d d d) The image is extended by replicating the last pixel.
  - 'mirror' (d c b | a b c d | c b a) The image is extended by reflecting about the center of the last pixel.
  - 'wrap' (a b c d | a b c d | a b c d) The image is extended by wrapping around to the opposite edge.
- cval (scalar, optional) – Value to fill past edges of image if mode is ‘constant’. Default is 0.0.
dask_image.ndfilters.threshold_local(image, block_size, method='gaussian', offset=0, mode='reflect', param=None, cval=0)

Compute a threshold mask image based on local pixel neighborhood.
Also known as adaptive or dynamic thresholding[1]_. The threshold value is the weighted mean for the local neighborhood of a pixel subtracted by a constant. Alternatively the threshold can be determined dynamically by a given function, using the ‘generic’ method.

**Parameters**

- **image** ((N, M) dask ndarray) – Input image.
- **block_size** (int or list/tuple/array) – Size of pixel neighborhood which is used to calculate the threshold value. (1) A single value for use in all dimensions or (2) A tuple, list, or array with length equal to image.ndim
- **method** ({'generic', 'gaussian', 'mean', 'median'}, optional) – Method used to determine adaptive threshold for local neighbourhood in weighted mean image.
  - ‘generic’: use custom function (see param parameter)
  - ‘gaussian’: apply gaussian filter (see param parameter for custom sigma value)
  - ‘mean’: apply arithmetic mean filter
  - ‘median’: apply median rank filter

By default the ‘gaussian’ method is used.
- **offset** (float, optional) – Constant subtracted from weighted mean of neighborhood to calculate the local threshold value. Default offset is 0.
- **mode** ({'reflect', 'constant', 'nearest', 'mirror', 'wrap'}, optional) – The mode parameter determines how the array borders are handled, where cval is the value when mode is equal to ‘constant’. Default is ‘reflect’.
- **param** ({int, function}, optional) – Either specify sigma for ‘gaussian’ method or function object for ‘generic’ method. This functions takes the flat array of local neighbourhood as a single argument and returns the calculated threshold for the centre pixel.
- **cval** (float, optional) – Value to fill past edges of input if mode is ‘constant’.

**Returns**

threshold – Threshold image. All pixels in the input image higher than the corresponding pixel in the threshold image are considered foreground.

**Return type** (N, M) dask ndarray

**References**

**Examples**

```python
>>> import dask.array as da
>>> image = da.random.random((1000, 1000), chunks=(100, 100))
>>> result = threshold_local(image, 15, 'gaussian')
```

dask_image.ndfilters.uniform_filter(image, size=3, mode='reflect', cval=0.0, origin=0)

Wrapped copy of “scipy.ndimage.filters.uniform_filter”

Excludes the output parameter as it would not work with Dask arrays.
Original docstring:

Multi-dimensional uniform filter.

Parameters

- **image** *(array_like)* – The image array.
- **size** *(int or sequence of ints, optional)* – The sizes of the uniform filter are given for each axis as a sequence, or as a single number, in which case the size is equal for all axes.
- **mode** *(str or sequence, optional)* – The mode parameter determines how the image array is extended when the filter overlaps a border. By passing a sequence of modes with length equal to the number of dimensions of the image array, different modes can be specified along each axis. Default value is 'reflect'. The valid values and their behavior is as follows:
  - `'reflect'` *(d c b a \ a b c d \ d c b a)* The image is extended by reflecting about the edge of the last pixel.
  - `'constant'` *(k k k k \ a b c d \ k k k k)* The image is extended by filling all values beyond the edge with the same constant value, defined by the *cval* parameter.
  - `'nearest'` *(a a a a \ a b c d \ d d d d)* The image is extended by replicating the last pixel.
  - `'mirror'` *(d c b \ a b c d \ c b a)* The image is extended by reflecting about the center of the last pixel.
  - `'wrap'` *(a b c d \ a b c d \ a b c d)* The image is extended by wrapping around to the opposite edge.
- **cval** *(scalar, optional)* – Value to fill past edges of image if mode is 'constant'. Default is 0.0.
- **origin** *(int or sequence, optional)* – Controls the placement of the filter on the image array’s pixels. A value of 0 (the default) centers the filter over the pixel, with positive values shifting the filter to the left, and negative ones to the right. By passing a sequence of origins with length equal to the number of dimensions of the image array, different shifts can be specified along each axis.

Returns **uniform_filter** – Filtered array. Has the same shape as *image*.

Return type **ndarray**

Notes

The multi-dimensional filter is implemented as a sequence of one-dimensional uniform filters. The intermediate arrays are stored in the same data type as the output. Therefore, for output types with a limited precision, the results may be imprecise because intermediate results may be stored with insufficient precision.
dask_image.ndfourier package

**dask_image.ndfourier.fourier_gaussian** *(image, sigma, n=-1, axis=-1)*

Multi-dimensional Gaussian fourier filter.

The array is multiplied with the fourier transform of a Gaussian kernel.

**Parameters**

- **image** *(array_like)* – The input image.
- **sigma** *(float or sequence)* – The sigma of the Gaussian kernel. If a float, `sigma` is the same for all axes. If a sequence, `sigma` has to contain one value for each axis.
- **n** *(int, optional)* – If `n` is negative (default), then the image is assumed to be the result of a complex fft. If `n` is larger than or equal to zero, the image is assumed to be the result of a real fft, and `n` gives the length of the array before transformation along the real transform direction.
- **axis** *(int, optional)* – The axis of the real transform.

**Returns** *fourier_gaussian*

**Return type** *Dask Array*

**Examples**

```python
>>> from scipy import ndimage, misc
>>> import numpy.fft
>>> import matplotlib.pyplot as plt

>>> fig, (ax1, ax2) = plt.subplots(1, 2)
>>> plt.gray()  # show the filtered result in grayscale
>>> ascent = misc.ascent()
>>> image = numpy.fft.fft2(ascent)
>>> result = ndimage.fourier_gaussian(image, sigma=4)
>>> result = numpy.fft.ifft2(result)
>>> ax1.imshow(ascent)
```

**dask_image.ndfourier.fourier_shift** *(image, shift, n=-1, axis=-1)*

Multi-dimensional fourier shift filter.

The array is multiplied with the fourier transform of a shift operation.

**Parameters**

- **image** *(array_like)* – The input image.
- **shift** *(float or sequence)* – The size of the box used for filtering. If a float, `shift` is the same for all axes. If a sequence, `shift` has to contain one value for each axis.
- **n** *(int, optional)* – If `n` is negative (default), then the image is assumed to be the result of a complex fft. If `n` is larger than or equal to zero, the image is assumed to be the result of a real fft, and `n` gives the length of the array before transformation along the real transform direction.
- **axis** *(int, optional)* – The axis of the real transform.

**Returns** *fourier_shift*

**Return type** *Dask Array*
dask-image Documentation, Release 0.4.0+0.g1322e24.dirty

Examples

```python
>>> from scipy import ndimage, misc
>>> import matplotlib.pyplot as plt
>>> import numpy.fft

>>> fig, (ax1, ax2) = plt.subplots(1, 2)
>>> plt.gray()  # show the filtered result in grayscale
>>> ascent = misc.ascent()
>>> image = numpy.fft.fft2(ascent)
>>> result = ndimage.fourier_shift(image, shift=200)
>>> result = numpy.fft.ifft2(result)
>>> ax1.imshow(ascent)
>>> ax2.imshow(result.real)  # the imaginary part is an artifact
>>> plt.show()
```

dask_image.ndfourier.fourier_uniform(image, size, n=-1, axis=-1)

Multi-dimensional uniform fourier filter.

The array is multiplied with the fourier transform of a box of given size.

**Parameters**

- `image (array_like)` – The input image.
- `size (float or sequence)` – The size of the box used for filtering. If a float, `size` is the same for all axes. If a sequence, `size` has to contain one value for each axis.
- `n (int, optional)` – If `n` is negative (default), then the image is assumed to be the result of a complex fft. If `n` is larger than or equal to zero, the image is assumed to be the result of a real fft, and `n` gives the length of the array before transformation along the real transform direction.
- `axis (int, optional)` – The axis of the real transform.

**Returns**

- `fourier_uniform` – The filtered image. If `output` is given as a parameter, None is returned.

**Return type**

Dask Array

Examples

```python
>>> from scipy import ndimage, misc
>>> import numpy.fft

>>> fig, (ax1, ax2) = plt.subplots(1, 2)
>>> plt.gray()  # show the filtered result in grayscale
>>> ascent = misc.ascent()
>>> image = numpy.fft.fft2(ascent)
>>> result = ndimage.fourier_uniform(image, size=20)
>>> result = numpy.fft.ifft2(result)
>>> ax1.imshow(ascent)
>>> ax2.imshow(result.real)  # the imaginary part is an artifact
>>> plt.show()
```
dask_image.ndmeasure package

dask_image.ndmeasure.area(image, label_image=None, index=None)
Find the area of specified subregions in an image.

Parameters
• image (ndarray) – N-D image data
• label_image (ndarray, optional) – Image features noted by integers. If None (default), returns area of total image dimensions.
• index (int or sequence of ints, optional) – Labels to include in output. If None (default), all values where non-zero label_image are used. The index argument only works when label_image is specified.

Returns area – Area of index selected regions from label_image.

Return type ndarray

Example

```python
>>> import dask.array as da
>>> image = da.random.random((3, 3))
>>> label_image = da.from_array(
    [[1, 1, 0],
    [1, 0, 3],
    [0, 7, 0]], chunks=(1, 3))

>>> # No labels given, returns area of total image dimensions
>>> area(image)
9

>>> # Combined area of all non-zero labels
>>> area(image, label_image).compute()
5

>>> # Areas of selected labels selected with the ´index´ keyword argument
>>> area(image, label_image, index=[0, 1, 2, 3]).compute()
dtype=int64
```

dask_image.ndmeasure.center_of_mass(image, label_image=None, index=None)
Find the center of mass over an image at specified subregions.

Parameters
• image (ndarray) – N-D image data
• label_image (ndarray, optional) – Image features noted by integers. If None (default), all values.
• index (int or sequence of ints, optional) – Labels to include in output. If None (default), all values where non-zero label_image are used. The index argument only works when label_image is specified.

Returns center_of_mass – Coordinates of centers-of-mass of image over the index selected regions from label_image.
Return type  ndarray

dask_image.ndmeasure.extrema(image, label_image=None, index=None)

Find the min and max with positions over an image at specified subregions.

Parameters

- **image (ndarray)** – N-D image data
- **label_image (ndarray, optional)** – Image features noted by integers. If None (default), all values.
- **index (int or sequence of ints, optional)** – Labels to include in output. If None (default), all values where non-zero label_image are used.

The `index` argument only works when `label_image` is specified.

Returns  minimums, maximums, min_positions, max_positions – Values and coordinates of minimums and maximums in each feature.

Return type  tuple of ndarrays

dask_image.ndmeasure.histogram(image, min, max, bins, label_image=None, index=None)

Find the histogram over an image at specified subregions.

Histogram calculates the frequency of values in an array within bins determined by `min`, `max`, and `bins`. The `label_image` and `index` keywords can limit the scope of the histogram to specified sub-regions within the array.

Parameters

- **image (ndarray)** – N-D image data
- **min (int)** – Minimum value of range of histogram bins.
- **max (int)** – Maximum value of range of histogram bins.
- **bins (int)** – Number of bins.
- **label_image (ndarray, optional)** – Image features noted by integers. If None (default), all values.
- **index (int or sequence of ints, optional)** – Labels to include in output. If None (default), all values where non-zero label_image are used.

The `index` argument only works when `label_image` is specified.

Returns  histogram – Histogram of `image` over the `index` selected regions from `label_image`.

Return type  ndarray

dask_image.ndmeasure.label(image, structure=None)

Label features in an array.

Parameters

- **image (ndarray)** – An array-like object to be labeled. Any non-zero values in image are counted as features and zero values are considered the background.
- **structure (ndarray, optional)** – A structuring element that defines feature connections. structure must be symmetric. If no structuring element is provided, one is automatically generated with a squared connectivity equal to one. That is, for a 2-D image array, the default structuring element is:
Returns

- **label** (*ndarray or int*) – An integer ndarray where each unique feature in `image` has a unique label in the returned array.
- **num_features** (*int*) – How many objects were found.

```python
dask_image.ndmeasure.labeled_comprehension(image, label_image, index, func, out_dtype, default, pass_positions=False)
```

Compute a function over an image at specified subregions.

Roughly equivalent to `[func(image[labels == i]) for i in index]`.

Sequentially applies an arbitrary function (that works on array_like image) to subsets of an n-D image array specified by `label_image` and `index`. The option exists to provide the function with positional parameters as the second argument.

Parameters

- **image** (*ndarray*) – N-D image data
- **label_image** (*ndarray, optional*) – Image features noted by integers. If None (default), all values.
- **index** (*int or sequence of ints, optional*) – Labels to include in output. If None (default), all values where non-zero `label_image` are used.

The index argument only works when `label_image` is specified.
- **func** (*callable*) – Python function to apply to `label_image` from `image`.
- **out_dtype** (*dtype*) – Dtype to use for `result`.
- **default** (*int, float or None*) – Default return value when a element of `index` does not exist in `label_image`.
- **pass_positions** (*bool, optional*) – If True, pass linear indices to `func` as a second argument. Default is False.

Returns `result` – Result of applying `func` on `image` over the `index` selected regions from `label_image`.

Return type *ndarray*

```python
dask_image.ndmeasure.maximum(image, label_image=None, index=None)
```

Find the maxima over an image at specified subregions.

Parameters

- **image** (*ndarray*) – N-D image data
- **label_image** (*ndarray, optional*) – Image features noted by integers. If None (default), all values.
- **index** (*int or sequence of ints, optional*) – Labels to include in output. If None (default), all values where non-zero `label_image` are used.

The index argument only works when `label_image` is specified.

Returns `maxima` – Maxima of `image` over the `index` selected regions from `label_image`.

Return type *ndarray*
dask_image.ndmeasure.maximum_position(image, label_image=None, index=None)

Find the positions of maxima over an image at specified subregions.

For each region specified by label_image, the position of the maximum value of image within the region is returned.

Parameters

- **image** (ndarray) – N-D image data
- **label_image** (ndarray, optional) – Image features noted by integers. If None (default), all values.
- **index** (int or sequence of ints, optional) – Labels to include in output. If None (default), all values where non-zero label_image are used.

The index argument only works when label_image is specified.

Returns **maxima_positions** – Maxima positions of image over the index selected regions from label_image.

Return type **ndarray**

dask_image.ndmeasure.mean(image, label_image=None, index=None)

Find the mean over an image at specified subregions.

Parameters

- **image** (ndarray) – N-D image data
- **label_image** (ndarray, optional) – Image features noted by integers. If None (default), all values.
- **index** (int or sequence of ints, optional) – Labels to include in output. If None (default), all values where non-zero label_image are used.

The index argument only works when label_image is specified.

Returns **means** – Mean of image over the index selected regions from label_image.

Return type **ndarray**

dask_image.ndmeasure.median(image, label_image=None, index=None)

Find the median over an image at specified subregions.

Parameters

- **image** (ndarray) – N-D image data
- **label_image** (ndarray, optional) – Image features noted by integers. If None (default), all values.
- **index** (int or sequence of ints, optional) – Labels to include in output. If None (default), all values where non-zero label_image are used.

The index argument only works when label_image is specified.

Returns **medians** – Median of image over the index selected regions from label_image.

Return type **ndarray**

dask_image.ndmeasure.minimum(image, label_image=None, index=None)

Find the minima over an image at specified subregions.

Parameters

- **image** (ndarray) – N-D image data
• **label_image** (*ndarray, optional*) – Image features noted by integers. If None (default), all values.

• **index**(int or sequence of ints, optional) – Labels to include in output. If None (default), all values where non-zero label_image are used.

  The index argument only works when label_image is specified.

**Returns**

- **minima** – Minima of image over the index selected regions from label_image.

**Return type**  ndarray

dask_image.ndmeasure.minimum_position(*image, label_image=None, index=None*)

Find the positions of minima over an image at specified subregions.

**Parameters**

- **image** (*ndarray*) – N-D image data

• **label_image** (*ndarray, optional*) – Image features noted by integers. If None (default), all values.

• **index**(int or sequence of ints, optional) – Labels to include in output. If None (default), all values where non-zero label_image are used.

  The index argument only works when label_image is specified.

**Returns**

- **minima_positions** – Maxima positions of image over the index selected regions from label_image.

**Return type**  ndarray

dask_image.ndmeasure.standard_deviation(*image, label_image=None, index=None*)

Find the standard deviation over an image at specified subregions.

**Parameters**

- **image** (*ndarray*) – N-D image data

• **label_image** (*ndarray, optional*) – Image features noted by integers. If None (default), all values.

• **index**(int or sequence of ints, optional) – Labels to include in output. If None (default), all values where non-zero label_image are used.

  The index argument only works when label_image is specified.

**Returns**

- **standard_deviation** – Standard deviation of image over the index selected regions from label_image.

**Return type**  ndarray

dask_image.ndmeasure.sum(*image, label_image=None, index=None*)

Find the sum over an image at specified subregions.

**Parameters**

- **image** (*ndarray*) – N-D image data

• **label_image** (*ndarray, optional*) – Image features noted by integers. If None (default), all values.

• **index**(int or sequence of ints, optional) – Labels to include in output. If None (default), all values where non-zero label_image are used.

  The index argument only works when label_image is specified.
Returns sum – Sum of image over the index selected regions from label_image.

Return type ndarray
dask_image.ndmeasure.variance(image, label_image=None, index=None)
Find the variance over an image at specified subregions.

Parameters

• **image** (*ndarray*) – N-D image data

• **label_image** (*ndarray, optional*) – Image features noted by integers. If None (default), all values.

• **index** (*int or sequence of ints, optional*) – Labels to include in output. If None (default), all values where non-zero label_image are used.

The index argument only works when label_image is specified.

Returns variance – Variance of image over the index selected regions from label_image.

Return type ndarray
dask_image.ndmorph package
dask_image.ndmorph.binary_closing(image, structure=None, iterations=1, origin=0)
Wrapped copy of “scipy.ndimage.morphology.binary_closing”

Excludes the output parameter as it would not work with Dask arrays.

Original docstring:

Multi-dimensional binary closing with the given structuring element.

Parameters

• **image** (*array_like*) – Binary array_like to be closed. Non-zero (True) elements form the subset to be closed.

• **structure** (*array_like, optional*) – Structuring element used for the closing. Non-zero elements are considered True. If no structuring element is provided an element is generated with a square connectivity equal to one (i.e., only nearest neighbors are connected to the center, diagonally-connected elements are not considered neighbors).

• **iterations** (*{int, float}, optional*) – The dilation step of the closing, then the erosion step are each repeated iterations times (one, by default). If iterations is less than 1, each operations is repeated until the result does not change anymore.

• **origin** (*int or tuple of ints, optional*) – Placement of the filter, by default 0.

• **mask** (*array_like, optional*) – If a mask is given, only those elements with a True value at the corresponding mask element are modified at each iteration.

New in version 1.1.0.

• **border_value** (*int (cast to 0 or 1), optional*) – Value at the border in the output array.

New in version 1.1.0.
• **brute_force** (boolean, optional) – Memory condition: if False, only the pixels whose value was changed in the last iteration are tracked as candidates to be updated in the current iteration; if true all pixels are considered as candidates for update, regardless of what happened in the previous iteration. False by default.

New in version 1.1.0.

**Returns**  
**binary_closing** – Closing of the image by the structuring element.

**Return type**  
ndarray of bools

**See also:**
grey_closing(),  
binary_opening(),  
binary_dilation(),  
binary_erosion(),  
generate_binary_structure()

**Notes**

*Closing* [1] is a mathematical morphology operation [2] that consists in the succession of a dilation and an erosion of the image with the same structuring element. Closing therefore fills holes smaller than the structuring element.

Together with *opening* (binary_opening), closing can be used for noise removal.

**References**

dask_image.ndmorph.binary_dilation(image, structure=None, iterations=1, mask=None, border_value=0, origin=0, brute_force=False)

Wrapped copy of “scipy.ndimage.morphology.binary_dilation”

Excludes the output parameter as it would not work with Dask arrays.

Original docstring:

Multi-dimensional binary dilation with the given structuring element.

**Parameters**

• **image** (array_like) – Binary array_like to be dilated. Non-zero (True) elements form the subset to be dilated.

• **structure** (array_like, optional) – Structuring element used for the dilation. Non-zero elements are considered True. If no structuring element is provided an element is generated with a square connectivity equal to one.

• **iterations** ([int, float], optional) – The dilation is repeated iterations times (one, by default). If iterations is less than 1, the dilation is repeated until the result does not change anymore.

• **mask** (array_like, optional) – If a mask is given, only those elements with a True value at the corresponding mask element are modified at each iteration.

• **origin** (int or tuple of ints, optional) – Placement of the filter, by default 0.

• **brute_force** (boolean, optional) – Memory condition: if False, only the pixels whose value was changed in the last iteration are tracked as candidates to be updated (dilated) in the current iteration; if True all pixels are considered as candidates for dilation, regardless of what happened in the previous iteration. False by default.

**Returns**  
**binary_dilation** – Dilation of the image by the structuring element.
Return type  ndarray of bools

See also:

grey_dilation(),  binary_erosion(),  binary_closing(),  binary_opening(),
generate_binary_structure()

Notes

Dilation [1] is a mathematical morphology operation [2] that uses a structuring element for expanding the shapes in an image. The binary dilation of an image by a structuring element is the locus of the points covered by the structuring element, when its center lies within the non-zero points of the image.

References

dask_image.ndmorph.binary_erosion(image,  structure=None,  iterations=1,  mask=None,  border_value=0,  origin=0,  brute_force=False)

Wrapped copy of “scipy.ndimage.morphology.binary_erosion”

Excludes the output parameter as it would not work with Dask arrays.

Original docstring:

Multi-dimensional binary erosion with a given structuring element.

Binary erosion is a mathematical morphology operation used for image processing.

Parameters

- **image (array_like)** – Binary image to be eroded. Non-zero (True) elements form the subset to be eroded.
- **structure (array_like, optional)** – Structuring element used for the erosion. Non-zero elements are considered True. If no structuring element is provided, an element is generated with a square connectivity equal to one.
- **iterations (int, float, optional)** – The erosion is repeated iterations times (one, by default). If iterations is less than 1, the erosion is repeated until the result does not change anymore.
- **mask (array_like, optional)** – If a mask is given, only those elements with a True value at the corresponding mask element are modified at each iteration.
- **origin (int or tuple of ints, optional)** – Placement of the filter, by default 0.
- **brute_force (boolean, optional)** – Memory condition: if False, only the pixels whose value was changed in the last iteration are tracked as candidates to be updated (eroded) in the current iteration; if True all pixels are considered as candidates for erosion, regardless of what happened in the previous iteration. False by default.

Returns  binary_erosion – Erosion of the image by the structuring element.

Return type  ndarray of bools

See also:

grey_erosion(),  binary_dilation(),  binary_closing(),  binary_opening(),
generate_binary_structure()
Erosion [1] is a mathematical morphology operation [2] that uses a structuring element for shrinking the shapes in an image. The binary erosion of an image by a structuring element is the locus of the points where a superimposition of the structuring element centered on the point is entirely contained in the set of non-zero elements of the image.

**References**

dask_image.ndmorph.binary_opening(image, structure=None, iterations=1, origin=0)

Wrapped copy of “scipy.ndimage.morphology.binary_opening”

Excludes the output parameter as it would not work with Dask arrays.

Original docstring:

Multi-dimensional binary opening with the given structuring element.

The opening of an image image by a structuring element is the dilation of the erosion of the image by the structuring element.

**Parameters**

- **image** (array_like) – Binary array_like to be opened. Non-zero (True) elements form the subset to be opened.
- **structure** (array_like, optional) – Structuring element used for the opening. Non-zero elements are considered True. If no structuring element is provided an element is generated with a square connectivity equal to one (i.e., only nearest neighbors are connected to the center, diagonally-connected elements are not considered neighbors).
- **iterations** ((int, float), optional) – The erosion step of the opening, then the dilation step are each repeated iterations times (one, by default). If iterations is less than 1, each operation is repeated until the result does not change anymore.
- **origin** (int or tuple of ints, optional) – Placement of the filter, by default 0.
- **mask** (array_like, optional) – If a mask is given, only those elements with a True value at the corresponding mask element are modified at each iteration.

New in version 1.1.0.
- **border_value** (int (cast to 0 or 1), optional) – Value at the border in the output array.

New in version 1.1.0.
- **brute_force** (boolean, optional) – Memory condition: if False, only the pixels whose value was changed in the last iteration are tracked as candidates to be updated in the current iteration; if true all pixels are considered as candidates for update, regardless of what happened in the previous iteration. False by default.

New in version 1.1.0.

**Returns** binary_opening – Opening of the image by the structuring element.

**Return type** ndarray of bools

See also:

grey_opening(), binary_closing(), binary_erosion(), binary_dilation(), generate_binary_structure()
Notes

Opening [1]_ is a mathematical morphology operation [2]_ that consists in the succession of an erosion and a
dilation of the image with the same structuring element. Opening therefore removes objects smaller than the
structuring element.

Together with closing (binary_closing), opening can be used for noise removal.

References

2.5 Contributing

Contributions are welcome, and they are greatly appreciated! Every little bit helps, and credit will always be given.

You can contribute in many ways:

2.5.1 Types of Contributions

Report Bugs


If you are reporting a bug, please include:

- Your operating system name and version.
- Any details about your local setup that might be helpful in troubleshooting.
- Detailed steps to reproduce the bug.

Fix Bugs

Look through the GitHub issues for bugs. Anything tagged with “bug” and “help wanted” is open to whoever wants
to implement it.

Implement Features

Look through the GitHub issues for features. Anything tagged with “enhancement” and “help wanted” is open to
whoever wants to implement it.

Write Documentation

dask-image could always use more documentation, whether as part of the official dask-image docs, in docstrings, or
even on the web in blog posts, articles, and such.

To build the documentation locally and preview your changes, first set up the conda environment for building the
dask-image documentation:

```bash
$ conda env create -f environment_doc.yml
$ conda activate dask_image_doc_env
```

This conda environment contains dask-image and its dependencies, sphinx, and the dask-sphinx-theme.

Next, build the documentation with sphinx:
Now you can preview the html documentation in your browser by opening the file: dask-image/docs/_build/html/index.html

Submit Feedback

The best way to send feedback is to file an issue at https://github.com/dask/dask-image/issues.

If you are proposing a feature:

- Explain in detail how it would work.
- Keep the scope as narrow as possible, to make it easier to implement.
- Remember that this is a volunteer-driven project, and that contributions are welcome :)
2.5.3 Pull Request Guidelines

Before you submit a pull request, check that it meets these guidelines:

1. The pull request should include tests.
2. If the pull request adds functionality, the docs should be updated. Put your new functionality into a function with a docstring, and add the feature to the list in README.rst.
3. The pull request should work for all supported Python versions. Check CI's and make sure that the tests pass for all supported Python versions and platforms.

2.5.4 Tips

To run a subset of tests:

```
$ py.test tests/test_dask_image.py
```

2.6 Credits

2.6.1 Development Lead

- John Kirkham <kirkhamj@janelia.hhmi.org>

2.6.2 Contributors

None yet. Why not be the first?

2.7 History

2.7.1 0.4.0 (2020-09-02)

We’re pleased to announce the release of dask-image 0.4.0!

Highlights

The major highlight of this release is support for cupy GPU arrays for dask-image subpackages imread and ndfilters. Cupy version 7.7.0 or higher is required to use this functionality. GPU support for the remaining dask-image subpackages (ndmorph, ndfourier, and ndmeasure) will be rolled out at a later date, beginning with ndmorph.

We also have a new function, threshold_local, similar to the scikit-image local threshold function.

Lastly, we’ve made more improvements to the user documentation, which includes work by new contributor @abhishht51.

New Features

- GPU support for ndfilters & imread modules (#151)
- threshold_local function for dask-image ndfilters (#112)

Improvements

- Add function coverage table to the dask-image docs (#155)
• Developer documentation: release guide (#142)
• Use tifffile for testing instead of scikit-image (#145)

3 authors added to this release (alphabetical)
• Abhisht Singh - @abhisht51
• Genevieve Buckley - @GenevieveBuckley
• jakirkham - @jakirkham

2 reviewers added to this release (alphabetical)
• Genevieve Buckley - @GenevieveBuckley
• Juan Nunez-Iglesias - @jni

2.7.2 0.3.0 (2020-06-06)

We’re pleased to announce the release of dask-image 0.3.0!

Highlights
• Python 3.8 is now supported (#131)
• Support for Python 2.7 and 3.5 has been dropped (#119) (#131)
• We have a dask-image quickstart guide (#108), available from the dask examples page: https://examples.dask.org/applications/image-processing.html

New Features
• Distributed labeling has been implemented (#94)
• Area measurement function added to dask_image.ndmeasure (#115)

Improvements
• Optimize out first where in label (#102)

Bug Fixes
• Bugfix in center_of_mass to correctly handle integer input arrays (#122)
• Test float cast in _norm_args (#105)
• Handle Dask’s renaming of atop to blockwise (#98)

API Changes
• Rename the input argument to image in the ndimage functions (#117)
• Rename labels in ndmeasure function arguments (#126)

Support
• Update installation instructions so conda is the preferred method (#88)
• Add Python 3.7 to Travis CI (#89)
• Add instructions for building docs with sphinx to CONTRIBUTING.rst (#90)
• Sort Python 3.7 requirements (#91)
• Use double equals for exact package versions (#92)
• Use flake8 (#93)
• Note Python 3.7 support (#95)
  • Fix the Travis MacOS builds (update XCode to version 9.4 and use matplotlib ‘Agg’ backend) (#113)

7 authors added to this release (alphabetical)
• Amir Khalighi - @akhalighi
• Elliana May - @Mause
• Genevieve Buckley - @GenevieveBuckley
• jakirkham - @jakirkham
• Jaromir Latal - @jermenkoo
• Juan Nunez-Iglesias - @jni
• timbo8 - @timbo8

2 reviewers added to this release (alphabetical)
• Genevieve Buckley - @GenevieveBuckley
• jakirkham - @jakirkham

2.7.3 0.2.0 (2018-10-10)
• Construct separate label masks in labeled_comprehension (#82)
• Use full to construct 1-D NumPy array (#83)
• Use NumPy’s ndindex in labeled_comprehension (#81)
• Cleanup test_labeled_comprehension_struct (#80)
• Use 1-D structured array fields for position-based kernels in ndmeasure (#79)
• Rewrite center_of_mass using labeled_comprehension (#78)
• Adjust extrema’s internal structured type handling (#77)
• Test labeled_comprehension with object type (#76)
• Rewrite histogram to use labeled_comprehension (#75)
• Use labeled_comprehension directly in more function in ndmeasure (#74)
• Update mean’s variables to match other functions (#73)
• Consolidate summation in _ravel_shape_indices (#72)
• Update HISTORY for 0.1.2 release (#71)
• Bump dask-sphinx-theme to 1.1.0 (#70)
2.7.4 0.1.2 (2018-09-17)

- Ensure *labeled_comprehension*'s default is 1D. (#69)
- Bump dask-sphinx-theme to 1.0.5. (#68)
- Use nout=2 in ndmeasure’s label. (#67)
- Use custom kernel for extrema. (#61)
- Handle structured dtype in labeled_comprehension. (#66)
- Fixes for *unravel_index*. (#65)
- Bump dask-sphinx-theme to 1.0.4. (#64)
- Unwrap some lines. (#63)
- Use dask-sphinx-theme. (#62)
- Refactor out *unravel_index* function. (#60)
- Divide sigma by -2. (#59)
- Use Python 3’s definition of division in Python 2. (#58)
- Force dtype of *prod* in _ravel_shape_indices. (#57)
- Drop vendored compatibility code. (#54)
- Drop vendored copy of indices and uses thereof. (#56)
- Drop duplicate utility tests from ndmorph. (#55)
- Refactor utility module for imread. (#53)
- Reuse ndfilter utility function in ndmorph. (#52)
- Cleanup freq_grid_i construction in _get_freq_grid. (#51)
- Use shared Python 2/3 compatibility module. (#50)
- Consolidate Python 2/3 compatibility code. (#49)
- Refactor Python 2/3 compatibility from imread. (#48)
- Perform 2 * pi first in _get_ang_freq_grid. (#47)
- Ensure J is negated first in fourier_shift. (#46)
- Breakout common changes in fourier_gaussian. (#45)
- Use conda-forge badge. (#44)

2.7.5 0.1.1 (2018-08-31)

- Fix a bug in an ndmeasure test of an internal function.

2.7. History
2.7.6 0.1.0 (2018-08-31)

- First release on PyPI.
- Pulls in content from dask-image org.
- Supports reading of image files into Dask.
- Provides basic N-D filters with options to extend.
- Provides a few N-D Fourier filters.
- Provides a few N-D morphological filters.
- Provides a few N-D measurement functions for label images.
- Has 100% line coverage in test suite.
CHAPTER
THREE

INDICES AND TABLES

• genindex
• modindex
• search
d

dask_image, 6
dask_image.dispatch, 6
dask_image.imread, 6
dask_image.ndfilters, 7
dask_image.ndfourier, 21
dask_image.ndmeasure, 23
dask_image.ndmorph, 28
INDEX

A
area() (in module dask_image.ndmeasure), 23

B
binary_closing() (in module dask_image.ndmorph), 28
binary_dilation() (in module dask_image.ndmorph), 29
binary_erosion() (in module dask_image.ndmorph), 30
binary_opening() (in module dask_image.ndmorph), 31

C
center_of_mass() (in module dask_image.ndmeasure), 23
convolve() (in module dask_image.ndfilters), 7
correlate() (in module dask_image.ndfilters), 8

D
dask_image module, 6
dask_image.dispatch module, 6
dask_image.imread module, 6
dask_image.ndfilters module, 7
dask_image.ndfourier module, 21
dask_image.ndmeasure module, 23
dask_image.ndmorph module, 28

E
extrema() (in module dask_image.ndmeasure), 24

F
fourier_gaussian() (in module dask_image.ndfourier), 21
fourier_shift() (in module dask_image.ndfourier), 21
fourier_uniform() (in module dask_image.ndfourier), 22

G
gaussian_filter() (in module dask_image.ndfilters), 8
gaussian_gradient_magnitude() (in module dask_image.ndfilters), 9
gaussian_laplace() (in module dask_image.ndfilters), 10
generic_filter() (in module dask_image.ndfilters), 11

H
histogram() (in module dask_image.ndmeasure), 24

I
imread() (in module dask_image.imread), 6

L
label() (in module dask_image.ndmeasure), 24
labeled_comprehension() (in module dask_image.ndmeasure), 24
laplace() (in module dask_image.ndfilters), 12

M
maximum() (in module dask_image.ndmeasure), 25
maximum_filter() (in module dask_image.ndfilters), 13
maximum_position() (in module dask_image.ndmeasure), 25
mean() (in module dask_image.ndmeasure), 26
median() (in module dask_image.ndmeasure), 26
median_filter() (in module dask_image.ndfilters), 14
minimum() (in module dask_image.ndmeasure), 26
minimum_filter() (in module dask_image.ndfilters), 15
minimum_position() (in module dask_image.ndmeasure), 27
module
dask_image, 6
dask_image.dispatch, 6
dask_image.imread, 6
dask_image.ndfilters, 7
dask_image.ndfourier, 21
dask_image.ndmeasure, 23
dask_image.ndmorph, 28

P
percentile_filter() (in module dask_image.ndfilters), 15
prewitt() (in module dask_image.ndfilters), 16

R
rank_filter() (in module dask_image.ndfilters), 17

S
sobel() (in module dask_image.ndfilters), 18
standard_deviation() (in module dask_image.ndmeasure), 27
sum() (in module dask_image.ndmeasure), 27

T
threshold_local() (in module dask_image.ndfilters), 18

U
uniform_filter() (in module dask_image.ndfilters), 19

V
variance() (in module dask_image.ndmeasure), 28